

Contrastive Pre-Training and Multiple Instance Learning for Predicting Tumor Microsatellite Instability

Ronald Nap, Mohammed Aburidi, and Roummel Marcia

University of California, Merced, CA, USA

July 15-19, 2024



This talk

Project goal: Predict tumor Microsatellite Instability from Whole Slide Images using Contrastive Learning and Multiple Instance Learning.

Whole Slide Image (WSI): A high-resolution digital scan of an entire microscope slide.

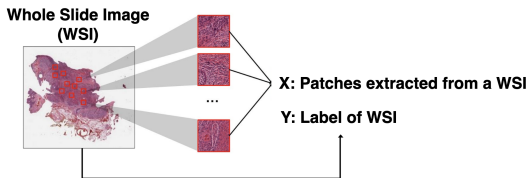
This talk

Project goal: Predict tumor Microsatellite Instability from Whole Slide Images using Contrastive Learning and Multiple Instance Learning.

Whole Slide Image (WSI): A high-resolution digital scan of an entire microscope slide.

Let

- $\mathbf{X} = \{x_i\}_{i=1}^N$: A set of N unlabeled patches extracted from a WSI.
- $\mathbf{Y} = \{y_j\}_{j=1}^K$: The set of K true WSI labels corresponding to different MSI statuses in a WSI.



Challenges in Direct WSI Classification:

Challenges in Direct WSI Classification:

- Substantial computational resources due to high dimensionality.
- **Tiny** details determine the classification of the **HUGE** image.

Our Approach:

Challenges in Direct WSI Classification:

- Substantial computational resources due to high dimensionality.
- **Tiny** details determine the classification of the **HUGE** image.

Our Approach:

- 1 Use Contrastive Learning to learn robust feature representations of patches.

Challenges in Direct WSI Classification:

- Substantial computational resources due to high dimensionality.
- **Tiny** details determine the classification of the **HUGE** image.

Our Approach:

- 1 Use Contrastive Learning to learn robust feature representations of patches.
- 2 Perform classification using feature vectors extracted from patches with Multiple Instance Learning.

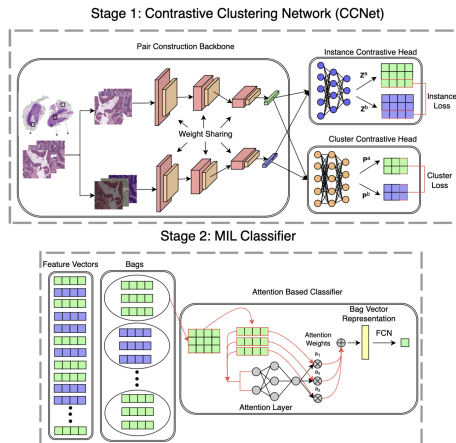
Our approach

Challenges in Direct WSI Classification:

- Substantial computational resources due to high dimensionality.
- **Tiny** details determine the classification of the **HUGE** image.

Our Approach:

- 1 Use Contrastive Learning to learn robust feature representations of patches.
- 2 Perform classification using feature vectors extracted from patches with Multiple Instance Learning.



1. Representation Learning with Contrastive Learning

Data Pair Creation:

Data pairs are generated for self-supervised representation learning. These pairs are created by applying various augmentations to the original image, resulting in two transformed versions, $\tilde{\mathbf{X}}^a$ and $\tilde{\mathbf{X}}^b$.

1. Representation Learning with Contrastive Learning

Data Pair Creation:

Data pairs are generated for self-supervised representation learning. These pairs are created by applying various augmentations to the original image, resulting in two transformed versions, $\tilde{\mathbf{X}}^a$ and $\tilde{\mathbf{X}}^b$.

The following augmentations are applied:

- Random cropping
- Color jittering
- Grayscale transformation
- Horizontal flipping
- Normalization

1. Representation Learning with Contrastive Learning

- **Feature Extraction:**

- Features are extracted using a shared ResNet $f(\cdot)$ encoder.

1. Representation Learning with Contrastive Learning

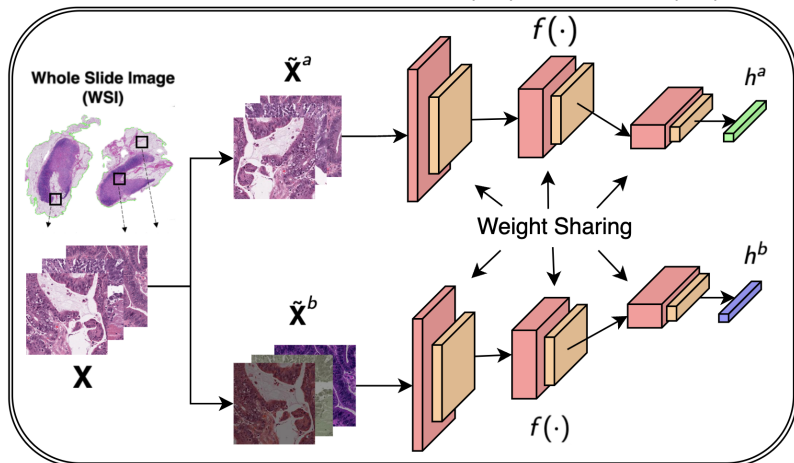
- **Feature Extraction:**

- Features are extracted using a shared ResNet $f(\cdot)$ encoder.
- Resulting in feature vectors $h^a = f(\tilde{\mathbf{X}}^a)$ and $h^b = f(\tilde{\mathbf{X}}^b)$.

1. Representation Learning with Contrastive Learning

● Feature Extraction:

- Features are extracted using a shared ResNet $f(\cdot)$ encoder.
- Resulting in feature vectors $h^a = f(\tilde{\mathbf{X}}^a)$ and $h^b = f(\tilde{\mathbf{X}}^b)$.



1. Representation Learning with Contrastive Learning

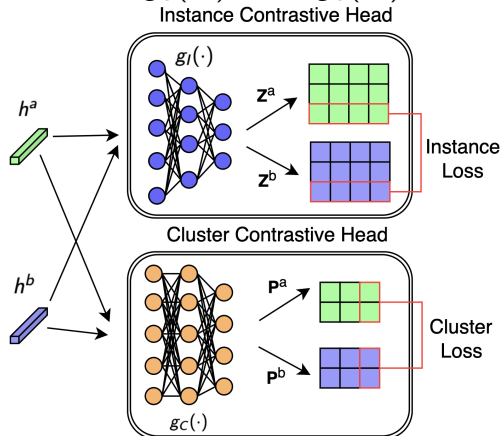
- **Projections:** Features are projected into row and column spaces using two separate MultiLayer Perceptions (MLPs) $g_I(\cdot)$ and $g_C(\cdot)$.

1. Representation Learning with Contrastive Learning

- **Projections:** Features are projected into row and column spaces using two separate MultiLayer Perceptions (MLPs) $g_I(\cdot)$ and $g_C(\cdot)$.
 - Instance space: $\mathbf{Z}^a = g_I(h^a)$, $\mathbf{Z}^b = g_I(h^b)$.
 - Cluster space: $\mathbf{P}^a = g_C(h^a)$, $\mathbf{P}^b = g_C(h^b)$.

1. Representation Learning with Contrastive Learning

- **Projections:** Features are projected into row and column spaces using two separate MultiLayer Perceptrons (MLPs) $g_I(\cdot)$ and $g_C(\cdot)$.
 - Instance space: $\mathbf{Z}^a = g_I(h^a)$, $\mathbf{Z}^b = g_I(h^b)$.
 - Cluster space: $\mathbf{P}^a = g_C(h^a)$, $\mathbf{P}^b = g_C(h^b)$.



1. Representation Learning with Contrastive Learning

Instance-Level Loss

1. Representation Learning with Contrastive Learning

Instance-Level Loss

$$\mathcal{L}_I = - \sum_{i=1}^N \log \frac{\exp(s(z_i^a, z_i^b)/\tau_I)}{\sum_{j=1}^N \exp(s(z_i^a, z_j^a)/\tau_I) + \exp(s(z_i^a, z_j^b)/\tau_I)} \quad (1)$$

where $s(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}$ is the cosine similarity.

1. Representation Learning with Contrastive Learning

Instance-Level Loss

$$\mathcal{L}_I = - \sum_{i=1}^N \log \frac{\exp(s(z_i^a, z_i^b)/\tau_I)}{\sum_{j=1}^N \exp(s(z_i^a, z_j^a)/\tau_I) + \exp(s(z_i^a, z_j^b)/\tau_I)} \quad (1)$$

where $s(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}$ is the cosine similarity. τ_I and τ_C are the instance-level and cluster-level temperature parameters (scaling factor for cosine similarity).

Cluster-Level Loss

1. Representation Learning with Contrastive Learning

Instance-Level Loss

$$\mathcal{L}_I = - \sum_{i=1}^N \log \frac{\exp(s(z_i^a, z_i^b)/\tau_I)}{\sum_{j=1}^N \exp(s(z_i^a, z_j^a)/\tau_I) + \exp(s(z_i^a, z_j^b)/\tau_I)} \quad (1)$$

where $s(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}$ is the cosine similarity. τ_I and τ_C are the instance-level and cluster-level temperature parameters (scaling factor for cosine similarity).

Cluster-Level Loss

$$\mathcal{L}_C = - \sum_{i=1}^K \log \frac{\exp(s(y_i^a, y_i^b)/\tau_C)}{\sum_{j=1}^K \exp(s(y_i^a, y_j^a)/\tau_C) + \exp(s(y_i^a, y_j^b)/\tau_C)} \quad (2)$$

1. Representation Learning with Contrastive Learning

Instance-Level Loss

$$\mathcal{L}_I = - \sum_{i=1}^N \log \frac{\exp(s(z_i^a, z_i^b)/\tau_I)}{\sum_{j=1}^N \exp(s(z_i^a, z_j^a)/\tau_I) + \exp(s(z_i^a, z_j^b)/\tau_I)} \quad (1)$$

where $s(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}$ is the cosine similarity. τ_I and τ_C are the instance-level and cluster-level temperature parameters (scaling factor for cosine similarity).

Cluster-Level Loss

$$\mathcal{L}_C = - \sum_{i=1}^K \log \frac{\exp(s(y_i^a, y_i^b)/\tau_C)}{\sum_{j=1}^K \exp(s(y_i^a, y_j^a)/\tau_C) + \exp(s(y_i^a, y_j^b)/\tau_C)} \quad (2)$$

Overall Loss Function

$$\mathcal{L} = \mathcal{L}_I + \mathcal{L}_C \quad (3)$$

1. Representation Learning with Contrastive Learning

Overall Workflow:

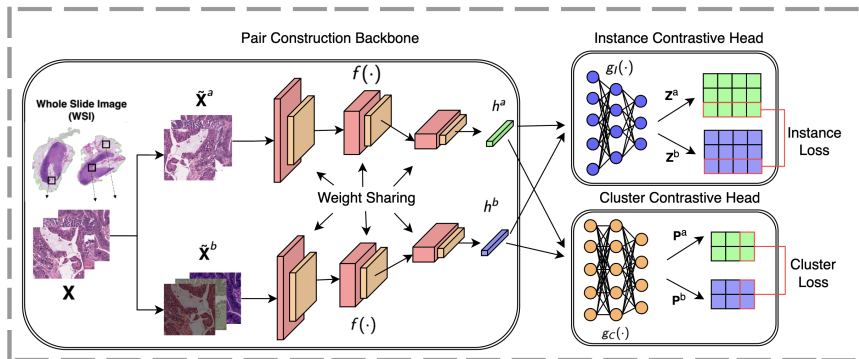
- Apply augmentations to create pairs of transformed patches.
- Use a shared ResNet encoder to extract feature vectors.
- Project feature vectors into instance and cluster spaces.
- Optimize the model to minimize the overall loss function.

1. Representation Learning with Contrastive Learning

Overall Workflow:

- Apply augmentations to create pairs of transformed patches.
- Use a shared ResNet encoder to extract feature vectors.
- Project feature vectors into instance and cluster spaces.
- Optimize the model to minimize the overall loss function.

Stage 1: Contrastive Clustering Network (CCNet)



2. Multiple Instance Learning

Multiple Instance Learning (MIL)

- MIL is a form of **weakly supervised learning**.
- Suited for scenarios with **uncertainty in labeling** individual data points $\{x_1, \dots, x_K\}$.
- Labels $Y \in \{0, 1\}$ are available at a **bag level** but individual labels instances $\{y_1, \dots, y_K\}$ are **unknown**.

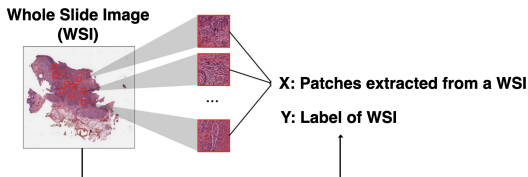
2. Multiple Instance Learning

Multiple Instance Learning (MIL)

- MIL is a form of **weakly supervised learning**.
- Suited for scenarios with **uncertainty in labeling** individual data points $\{x_1, \dots, x_K\}$.
- Labels $Y \in \{0, 1\}$ are available at a **bag level** but individual labels instances $\{y_1, \dots, y_K\}$ are **unknown**.

Context: Whole Slide Image (WSI) Analysis

- Treats each WSI as a collection of instances (patches).
- Effective due to the complexities and expansiveness of WSIs.
- Focus on **combined characteristics** of patches.



2. Multiple Instance Learning

MIL classifiers utilize a trainable attention mechanism to concentrate on the most informative instances within each bag.

2. Multiple Instance Learning

MIL classifiers utilize a trainable attention mechanism to concentrate on the most informative instances within each bag. This process involves an MLP attention network equipped with parameters \mathbf{W} , \mathbf{V} , and \mathbf{U} to allocate a weight a_k for each embedded instance \mathbf{z}_k .

2. Multiple Instance Learning

MIL classifiers utilize a trainable attention mechanism to concentrate on the most informative instances within each bag. This process involves an MLP attention network equipped with parameters \mathbf{W} , \mathbf{V} , and \mathbf{U} to allocate a weight a_k for each embedded instance \mathbf{z}_k .

$$a_k = \frac{\exp\{\mathbf{W}^\top (\tanh(\mathbf{V}\mathbf{z}_k) \odot \text{sigm}(\mathbf{U}\mathbf{z}_k))\}}{\sum_{j=1}^N \exp\{\mathbf{W}^\top (\tanh(\mathbf{V}\mathbf{z}_j) \odot \text{sigm}(\mathbf{U}\mathbf{z}_j))\}} \quad (4)$$

where $\text{sigm}(\cdot)$ is the sigmoid function, and \odot is the element-wise product, N is the number of the embedded instance vectors in a bag.

2. Multiple Instance Learning

MIL classifiers utilize a trainable attention mechanism to concentrate on the most informative instances within each bag. This process involves an MLP attention network equipped with parameters \mathbf{W} , \mathbf{V} , and \mathbf{U} to allocate a weight a_k for each embedded instance \mathbf{z}_k .

$$a_k = \frac{\exp\{\mathbf{W}^\top (\tanh(\mathbf{V}\mathbf{z}_k) \odot \text{sigm}(\mathbf{U}\mathbf{z}_k))\}}{\sum_{j=1}^N \exp\{\mathbf{W}^\top (\tanh(\mathbf{V}\mathbf{z}_j) \odot \text{sigm}(\mathbf{U}\mathbf{z}_j))\}} \quad (4)$$

where $\text{sigm}(\cdot)$ is the sigmoid function, and \odot is the element-wise product, N is the number of the embedded instance vectors in a bag.

$$\mu = \frac{1}{N} \sum_{k=1}^N a_k \mathbf{z}_k \quad (5)$$

The overall bag representation is computed by the weighted mean μ of these instance embeddings as shown above.

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .
 - δ - Smoothness parameter ensuring differentiability.
- Smooth SVM Loss for bag x_j is defined as:

$$l(y_j, f(x_j), \delta) = \begin{cases} \frac{1}{N} \sum_{i=1}^N \frac{1}{2\delta} \xi_i^2 & \text{if } \xi_i \leq \delta \\ \frac{1}{N} \sum_{i=1}^N (\xi_i - \frac{\delta}{2}) & \text{otherwise} \end{cases}$$

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .
 - δ - Smoothness parameter ensuring differentiability.
- Smooth SVM Loss for bag x_j is defined as:

$$l(y_j, f(x_j), \delta) = \begin{cases} \frac{1}{N} \sum_{i=1}^N \frac{1}{2\delta} \xi_i^2 & \text{if } \xi_i \leq \delta \\ \frac{1}{N} \sum_{i=1}^N (\xi_i - \frac{\delta}{2}) & \text{otherwise} \end{cases}$$

- **Kullback Leibler (KL) Divergence Regularization:**

- Acts as a regularizer applied with SVM Loss.

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .
 - δ - Smoothness parameter ensuring differentiability.
- Smooth SVM Loss for bag x_j is defined as:

$$l(y_j, f(x_j), \delta) = \begin{cases} \frac{1}{N} \sum_{i=1}^N \frac{1}{2\delta} \xi_i^2 & \text{if } \xi_i \leq \delta \\ \frac{1}{N} \sum_{i=1}^N (\xi_i - \frac{\delta}{2}) & \text{otherwise} \end{cases}$$

- **Kullback Leibler (KL) Divergence Regularization:**

- Acts as a regularizer applied with SVM Loss.
 - M - Total number of bags, N - Number of instances in bag j .
 - A_{ji} - Attention weight of instance i in bag j , U_{ji} - Uniform distribution value for instance i in bag j .

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .
 - δ - Smoothness parameter ensuring differentiability.
- Smooth SVM Loss for bag x_j is defined as:

$$l(y_j, f(x_j), \delta) = \begin{cases} \frac{1}{N} \sum_{i=1}^N \frac{1}{2\delta} \xi_i^2 & \text{if } \xi_i \leq \delta \\ \frac{1}{N} \sum_{i=1}^N (\xi_i - \frac{\delta}{2}) & \text{otherwise} \end{cases}$$

- **Kullback Leibler (KL) Divergence Regularization:**

- Acts as a regularizer applied with SVM Loss.
 - M - Total number of bags, N - Number of instances in bag j .
 - A_{ji} - Attention weight of instance i in bag j , U_{ji} - Uniform distribution value for instance i in bag j .
- Given by:

$$\text{KL Divergence} = \frac{1}{M} \sum_{j=1}^M \sum_{i=1}^N A_{ji} \log \left(\frac{A_{ji}}{U_{ji}} \right)$$

2. Multiple Instance Learning

MIL Loss + Regularizer:

- **Support Vector Machine (SVM) Loss:**

- For each bag x_j with label y_j , define $\xi_i = \max(0, 1 - \zeta_i \times y_j)$, where:
 - ζ_i - The predicted logit for instance i within the bag.
 - ξ_i - The hinge loss term for instance i .
 - δ - Smoothness parameter ensuring differentiability.
- Smooth SVM Loss for bag x_j is defined as:

$$l(y_j, f(x_j), \delta) = \begin{cases} \frac{1}{N} \sum_{i=1}^N \frac{1}{2\delta} \xi_i^2 & \text{if } \xi_i \leq \delta \\ \frac{1}{N} \sum_{i=1}^N (\xi_i - \frac{\delta}{2}) & \text{otherwise} \end{cases}$$

- **Kullback Leibler (KL) Divergence Regularization:**

- Acts as a regularizer applied with SVM Loss.
 - M - Total number of bags, N - Number of instances in bag j .
 - A_{ji} - Attention weight of instance i in bag j , U_{ji} - Uniform distribution value for instance i in bag j .
- Given by:

$$\text{KL Divergence} = \frac{1}{M} \sum_{j=1}^M \sum_{i=1}^N A_{ji} \log \left(\frac{A_{ji}}{U_{ji}} \right)$$

- We found that promoting uniform attention within each bag helped prevent overfitting to a few negative instances.

2. Multiple Instance Learning

Overall Workflow:

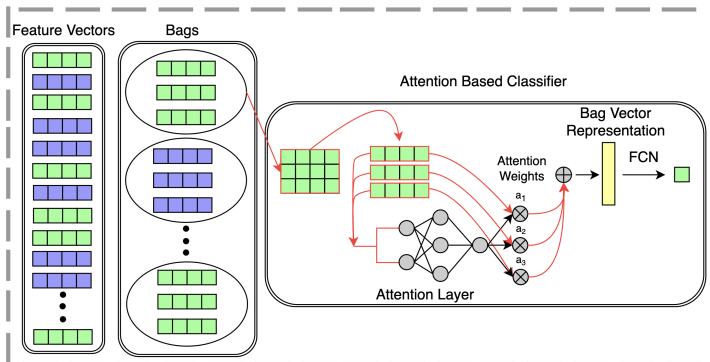
- Extract patches from WSIs.
- Learn instance-level features using Stage 1 (CCNet).
- Aggregate instance features to form a bag-level representation.
- Classify the bag-level representation to predict MSI status.

2. Multiple Instance Learning

Overall Workflow:

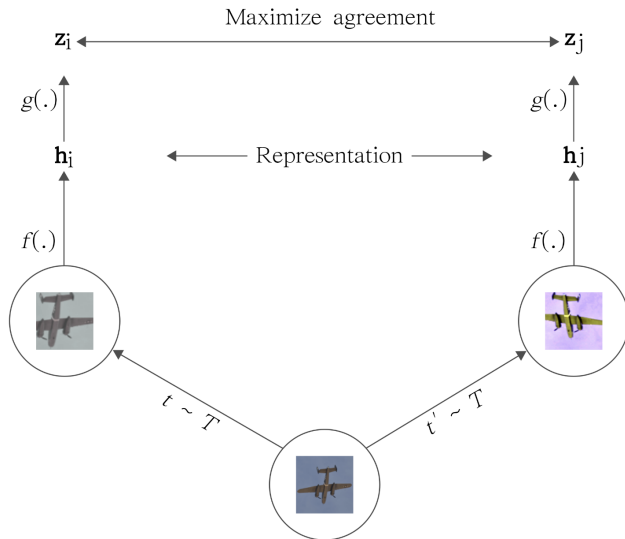
- Extract patches from WSIs.
- Learn instance-level features using Stage 1 (CCNet).
- Aggregate instance features to form a bag-level representation.
- Classify the bag-level representation to predict MSI status.

Stage 2: MIL Classifier



3. Numerical results: SimCLR

Contrary to our feature extractor (CCNet), SimCLR only utilizes an instance-level projection head for training.



3. Numerical results: Datasets

Dataset:

- We utilize two image datasets obtained from The Cancer Genome Atlas (TCGA) cohort:
 - The **Colorectal Cancer (CRC) dataset** was utilized for comparative analysis.
 - The **Stomach Adenocarcinoma (STAD) dataset** was employed to externally validate our model.

3. Numerical results: Datasets

Dataset:

- We utilize two image datasets obtained from The Cancer Genome Atlas (TCGA) cohort:
 - The **Colorectal Cancer (CRC) dataset** was utilized for comparative analysis.
 - The **Stomach Adenocarcinoma (STAD) dataset** was employed to externally validate our model.

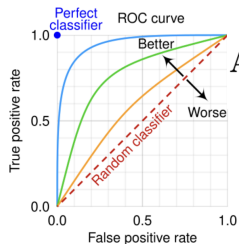
Evaluation:

- We partitioned the training data into 5-folds for cross-validation and reserved the testing split for final validation.

Dataset	Label	# of WSIs		# of Patches		# of Bags	
		Train	Test	Train	Test	Train	Test
CRC	MSI	39	26	46,704	29,335	1850	1122
	MSS	221	74	46,704	70,569	1757	2787
STAD	MSI	35	25	50,285	27,904	N/A	N/A
	MSS	150	74	50,285	90,104	N/A	N/A

3. Numerical results: Evaluation metrics

Area Under the Receiver Operating Characteristic (AUROC)



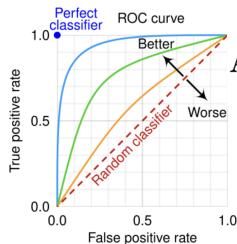
$$\text{AUROC} = \frac{1}{2} \sum_i (\text{TPR}_i + \text{TPR}_{i-1}) \times (\text{FPR}_i - \text{FPR}_{i-1})$$

$$\text{TPR} = \frac{TP}{TP + FN}$$

$$\text{FPR} = \frac{FP}{TN + FP}$$

3. Numerical results: Evaluation metrics

Area Under the Receiver Operating Characteristic (AUROC)



$$\text{AUROC} = \frac{1}{2} \sum_i (\text{TPR}_i + \text{TPR}_{i-1}) \times (\text{FPR}_i - \text{FPR}_{i-1})$$

$$\text{TPR} = \frac{TP}{TP + FN}$$

$$\text{FPR} = \frac{FP}{TN + FP}$$

F1 Score (F1)

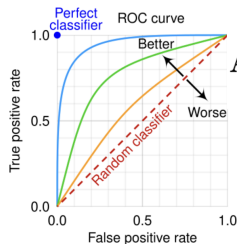
True positive (TP)	False negative (FN)
False positive (FP)	True negative (TN)

$$F1 = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$

$$\text{Precision} = \frac{TP}{TP + FP} \quad \text{Recall} = \frac{TP}{TP + FN}$$

3. Numerical results: Evaluation metrics

Area Under the Receiver Operating Characteristic (AUROC)



$$\text{AUROC} = \frac{1}{2} \sum_i (\text{TPR}_i + \text{TPR}_{i-1}) \times (\text{FPR}_i - \text{FPR}_{i-1})$$

$$\text{TPR} = \frac{TP}{TP + FN}$$

$$\text{FPR} = \frac{FP}{TN + FP}$$

F1 Score (F1)

True positive (TP)	False negative (FN)
False positive (FP)	True negative (TN)

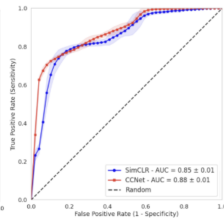
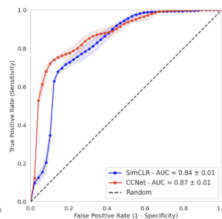
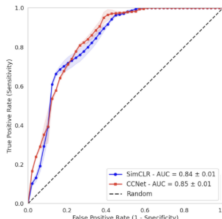
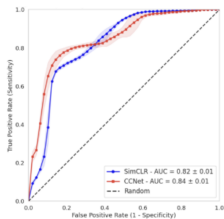
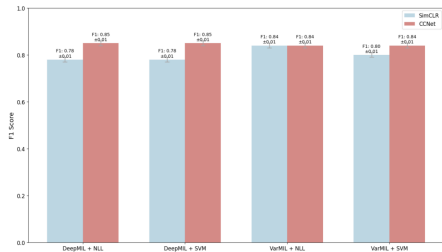
$$F1 = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$

$$\text{Precision} = \frac{TP}{TP + FP} \quad \text{Recall} = \frac{TP}{TP + FN}$$

Both measures values between 0 and 1 with **higher values indicating better results**.

3. Numerical results: CRC Dataset

- To ensure a comprehensive evaluation, we compute the mean and standard deviation of AUROC and F1 scores across five folds.
- We compare the performance of SimCLR with our CCNet extractor.
- We evaluate the efficacy of SVM loss compared to the conventional Negative Log-Likelihood (NLL) loss.
- We employ two attention-based MIL classifiers, DeepMIL and VarMIL, and assess the performance of each model configuration.



3. Numerical results: Transfer Learning

Motivation for Transfer Learning:

- In medical imaging, labeled data scarcity limits model training.
- Transfer learning leverages pre-trained models to enhance performance on related tasks.

3. Numerical results: Transfer Learning

Motivation for Transfer Learning:

- In medical imaging, labeled data scarcity limits model training.
- Transfer learning leverages pre-trained models to enhance performance on related tasks.

Experiment:

- We explore the performance of ResNet18 pretrained on ImageNet, SimCLR pre-trained on STAD and CCNet pre-trained on STAD.
- We utilize these pre-trained extractors to generate feature vectors for input for MIL Classification.

3. Numerical results: Transfer Learning

Motivation for Transfer Learning:

- In medical imaging, labeled data scarcity limits model training.
- Transfer learning leverages pre-trained models to enhance performance on related tasks.

Experiment:

- We explore the performance of ResNet18 pretrained on ImageNet, SimCLR pre-trained on STAD and CCNet pre-trained on STAD.
- We utilize these pre-trained extractors to generate feature vectors for input for MIL Classification.

Key Findings:

- CCNet, achieved better AUROC and F1 scores than SimCLR, demonstrating effective feature extraction.

Extractor	Classifier	Loss	AUROC	F1
ResNet18	DeepMIL	NLL	0.58 ± 0.01	0.67 ± 0.01
		SVM	0.58 ± 0.01	0.69 ± 0.01
	VarMIL	NLL	0.59 ± 0.01	0.69 ± 0.01
		SVM	0.59 ± 0.01	0.69 ± 0.01
SimCLR	DeepMIL	NLL	0.81 ± 0.01	0.82 ± 0.01
		SVM	0.82 ± 0.01	0.81 ± 0.01
	VarMIL	NLL	0.78 ± 0.01	0.82 ± 0.01
		SVM	0.81 ± 0.01	0.81 ± 0.01
CCNet	DeepMIL	NLL	0.81 ± 0.01	0.81 ± 0.01
		SVM	0.83 ± 0.01	0.82 ± 0.01
	VarMIL	NLL	0.81 ± 0.01	0.83 ± 0.01
		SVM	0.83 ± 0.01	0.81 ± 0.01

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.
- 2 Model incorporates Contrastive Learning and Multiple Instance Learning.

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.
- 2 Model incorporates Contrastive Learning and Multiple Instance Learning.
- 3 Conducted comparisons to state-of-the-art models.

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.
- 2 Model incorporates Contrastive Learning and Multiple Instance Learning.
- 3 Conducted comparisons to state-of-the-art models.
- 4 Conducted evaluation on two real-world histopathology cancers datasets: Colorectal (CRC) and Stomach (STAD) cancers.

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.
- 2 Model incorporates Contrastive Learning and Multiple Instance Learning.
- 3 Conducted comparisons to state-of-the-art models.
- 4 Conducted evaluation on two real-world histopathology cancers datasets: Colorectal (CRC) and Stomach (STAD) cancers.
- 5 Results from our proposed model improve upon existing methods.

4. Summary

- 1 Proposed a framework for predicting tumor Microsatellite Instability from Whole Slide Images.
- 2 Model incorporates Contrastive Learning and Multiple Instance Learning.
- 3 Conducted comparisons to state-of-the-art models.
- 4 Conducted evaluation on two real-world histopathology cancers datasets: Colorectal (CRC) and Stomach (STAD) cancers.
- 5 Results from our proposed model improve upon existing methods.



Thank You!